La méthode ICS pour détecter des atypiques en multivarié

Anne RUIZ-GAZEN¹

Co-authors: Aurore ARCHIMBAUD¹ Klaus NORDHAUSEN²

TSE-R, University of Toulouse 1 Capitole, France.
 CSTAT, Vienna University of Technology, Austria.

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Outlier definition and detection

- Let us consider $\mathbf{X}_n = (\mathbf{x}_1, \dots, \mathbf{x}_n)'$ a *p*-variate dataset.
- "An outlier is an observation which deviates so much from the other observations as to arouse suspicious that is was generated by a different mechanism." (Hawkins, 1980).
- For one variable x and n observations x₁,..., x_n, a simple rule is to look at the large values of:

$$\frac{|x_i - \bar{x}_n|}{\hat{\sigma}_n}$$
, for $i = 1, \dots, n$

The generalization of this rule to the multivariate case is the Mahalanobis distance of each observation to the mean:

$$\mathsf{MD}^2(\boldsymbol{x}_i) = ||\mathrm{COV}(\boldsymbol{X}_n)^{-1/2}(\boldsymbol{x}_i - \bar{\boldsymbol{x}}_n)||^2$$

where $\bar{\mathbf{x}}_n$ denotes the empirical mean and $\text{COV}(\mathbf{X}_n)$ the empirical covariance matrix.

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The Mahalanobis distance (sample version)

Classical measure for multivariate outlier detection:

$$\mathsf{MD}^{2}(\mathbf{x}_{i}) = ||\mathrm{COV}(\mathbf{X}_{n})^{-1/2}(\mathbf{x}_{i} - \bar{\mathbf{x}}_{n})||^{2}$$

where $\bar{\mathbf{x}}_n$ denotes the empirical mean and $\text{COV}(\mathbf{X}_n)$ the empirical covariance matrix.

An observation \mathbf{x}_i is identified as an outlier if:

$$\mathsf{MD}^2(\mathbf{x}_i) \geq c_{p,1-lpha}$$

with $c_{p,1-\alpha}$ the $(1 - \alpha)$ -th quantile of a χ^2_p distribution.

► Alternative: use a robust version based on the MCD¹ estimators.

¹Minimum Covariance Determinant: reweighted empirical mean and covariance estimators of the MCD subset based on the $h \approx \alpha * n$ observations whose covariance matrix has the smallest determinant.

The Mahalanobis distance (sample version)

Tolerance ellipse (97.5%)



V1

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The Mahalanobis distance (functional version)

- Functional version: X is a *p*-variate random vector, *F*_X its cumulative distribution function and m(*F*_X) an affine equivariant location estimator.
- Let P_p be the set of all symmetric positive definite matrices of order p.
- A scatter functional is defined as a matrix V(F_X) ∈ P_p, uniquely defined at F_X, which is affine equivariant in the sense that:

$$\mathbf{V}(F_{\mathbf{AX}+\gamma}) = \mathbf{AV}(F_{\mathbf{X}})\mathbf{A}',$$

for all $p \times p$ non-singular matrices **A** and all $\gamma \in \Re^p$.

The Mahalanobis distance:

$$d^{2}(\mathbf{X}) = (\mathbf{X} - \mathbf{m}(F_{\mathbf{X}}))' \mathbf{V}(F_{\mathbf{X}})^{-1} (\mathbf{X} - \mathbf{m}(F_{\mathbf{X}}))$$

•
$$d^2(\mathbf{X})$$
 is affine invariant: $d^2(\mathbf{AX} + \gamma) = d^2(\mathbf{X})$

Limitation of the Mahalanobis distance

Classical measure for multivariate outlier detection:

$$d^2(\mathbf{X}) = (\mathbf{X} - \mathbb{E}(\mathbf{X}))' \text{COV}(\mathbf{X})^{-1} (\mathbf{X} - \mathbb{E}(\mathbf{X})).$$

Let us consider the following model (M) which is a mixture of (q+1) Gaussian distributions:

$$\mathbf{X} \sim \underbrace{(1-\epsilon)\mathcal{N}(\boldsymbol{\mu}_0, \boldsymbol{\Sigma}_W)}_{\text{majority of the data}} + \underbrace{\sum_{h=1}^{q} \epsilon_h \mathcal{N}(\boldsymbol{\mu}_h, \boldsymbol{\Sigma}_W)}_{\text{clustered outliers}}, \text{ where } \epsilon = \sum_{h=1}^{q} \epsilon_h < 0.5$$

We have: $\mathbb{E}(\mathbf{X}) = (1 - \epsilon) \mu_0 + \sum_{h=1}^{q} \epsilon_h \mu_h \text{ and } \operatorname{COV}(\mathbf{X}) = \mathbf{\Sigma}_W + \mathbf{\Sigma}_B, \text{ with}$ $\mathbf{\Sigma}_B = (1 - \epsilon)(\mu_0 - \mu_{\mathbf{X}})(\mu_0 - \mu_{\mathbf{X}})' + \sum_{h=1}^{q} \epsilon_h(\mu_h - \mu_{\mathbf{X}})(\mu_h - \mu_{\mathbf{X}})'.$

Limitation of the Mahalanobis distance

"Non-outlier" observations $\mathbf{X}_{no} \sim \mathcal{N}(\boldsymbol{\mu}_0, \boldsymbol{\Sigma}_W)$,

"Outlier" observations $\mathbf{X}_{o,h} \sim \mathcal{N}(\boldsymbol{\mu}_h, \boldsymbol{\Sigma}_W)$, $\mathbf{X}_{no} \perp \mathbf{X}_{o,h}$, for $h = 1, \dots, q$

Proposition

Assuming that q is fixed and p becomes large, the distribution of the difference:

$$\frac{1}{2\sqrt{p}}\left(d^{2}(\mathbf{X}_{o,h})-d^{2}(\mathbf{X}_{no})-\mathbb{E}\left(d^{2}(\mathbf{X}_{o,h})-d^{2}(\mathbf{X}_{no})\right)\right)\xrightarrow[p\to\infty]{\mathcal{L}}\mathcal{N}(0,1)$$

where the expectation $\mathbb{E}\left(d^2(\mathbf{X}_{o,h}) - d^2(\mathbf{X}_{no})\right)$ does not depend on the dimension p.

Thus, the probability of finding outliers decreases when the dimension p increases.

A similar result is also derived for the robust case (when considering Σ_W instead of COV(X)).

20 obs $\sim \mathcal{N}_{p}(\mu_{1}, \mathbf{W})$ & 980 obs $\sim \mathcal{N}_{p}(0, \mathbf{W})$ with $\mu_1 = (6, 0, \dots, 0)'$, $\mathbf{W} = \text{diag}(1, 4, \dots, 4)$, n = 1000, 2% of outliers and p = 6, 25, 50.



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ICS Tyler et al., 2009

Simultaneous diagonalization of two scatter matrices V₁ and V₂:

 $\mathbf{V}_1^{-1}\mathbf{V}_2\mathbf{B}'=\mathbf{B}'\mathbf{D}$

where the diagonal matrix **D** contains the eigenvalues ρ_1, \ldots, ρ_p of $V_1^{-1}V_2$ in decreasing order and $\mathbf{B} = (\mathbf{b}_1, \ldots, \mathbf{b}_p)'$ contains the corresponding eigenvectors as its rows such that: $\mathbf{B}V_1\mathbf{B}' = \mathbf{I}_p$.

New components:

$$\mathbf{Z} = \mathbf{B}(\mathbf{X} - \mathbf{m}_1)$$

with \mathbf{m}_1 being a location estimator associated with \mathbf{V}_1 .

- Many possibilities for V₁ and V₂.
- ▶ For example, $V_1 = \text{COV}(X)$ and $V_2 = \text{COV}_4(X)$ with

$$\operatorname{COV}_4(\mathbf{X}) = rac{1}{p+2} \operatorname{\mathbb{E}} \left[d^2(\mathbf{X}) (\mathbf{X} - \operatorname{\mathbb{E}}(\mathbf{X})) (\mathbf{X} - \operatorname{\mathbb{E}}(\mathbf{X}))'
ight].$$

M-estimators, MCD estimators,...

ICS

Focusing only on the first eigenvalue and the first eigenvector, it is equivalent to maximizing the ratio:

$$\mathcal{K}(\mathbf{b}) = rac{\mathbf{b}' \mathbf{V}_2 \mathbf{b}}{\mathbf{b}' \mathbf{V}_1 \mathbf{b}}$$

where ρ_1 is the maximal possible value of $\mathcal{K}(\mathbf{b})$ over $\mathbf{b} \in \Re^{\rho}$ which is achieved in the direction of the eigenvector \mathbf{b}_1 . This ratio can be seen as a generalized measure of kurtosis.

- ICS follows the same "philosophy" as PCA. However, it differs from PCA which maximizes a variance criterion and which is only orthogonally invariant.
- In a different (supervised) context where the groups are known, one can use the between and within covariance matrices as V₁ and V₂ which leads to Discriminant Analysis.

Property of the components Under the model (M):

$$\mathbf{X} \sim (1-\epsilon) \mathcal{N}(oldsymbol{\mu}_0, oldsymbol{\Sigma}_W) + \sum_{h=1}^q \epsilon_h \mathcal{N}(oldsymbol{\mu}_h, oldsymbol{\Sigma}_W),$$

where $\epsilon = \sum_{h=1}^{q} \epsilon_h < 0.5$, $\mu_1 - \mu_0, \dots, \mu_q - \mu_0$ span some *q*-dimensional hyperplane.

Theorem (Tyler et al., 2009)

Suppose that the roots ρ_1, \ldots, ρ_p consist of *m* distinct values, say $\rho_{(1)}, \ldots, \rho_{(m)}$, with $\rho_{(k)}$ having multiplicity p_k for $k = 1, \ldots, m$ and hence $p_1 + \cdots + p_m = p$. There is at least one root $\rho_{(k)}$ with multiplicity greater than or equal to p - q. If no root has multiplicity greater than p - q, then there is a root with multiplicity p - q, say $\rho_{(j)}$, such that

$$\operatorname{span}\{\boldsymbol{\Sigma}_W^{-1}(\boldsymbol{\mu}_k-\boldsymbol{\mu}_0)|k=1,\ldots,q\}=\operatorname{span}\{\boldsymbol{\mathsf{B}}_q\}$$

where $\mathbf{B}_q = (\mathbf{b}_1, \dots, \mathbf{b}_{p_1 + \dots + p_{j-1}}, \mathbf{b}_{p_1 + \dots + p_{j+1}}, \dots, \mathbf{b}_p).$

 \Rightarrow Fisher's Linear Discriminant subspace even though the groups are

unknown

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If $V_1 = COV(X)$ and $V_2 = COV_4(X)$

Mean-shift outlier model (q = 1)

 $\mathbf{X} \sim (1 - \epsilon) \mathcal{N}(\mathbf{0}_{p}, \mathbf{\Sigma}_{1}) + \epsilon \mathcal{N}(\mu, \mathbf{\Sigma}_{1}), \text{ with } \epsilon < 0.5 \text{ and } \mu \neq \mathbf{0}_{p} \text{ a } p$ -vector.

The eigenvalues of $COV^{-1}(\mathbf{X})COV_4(\mathbf{X})$ are such that either:

(a) $\rho_1 > \rho_2 = \dots = \rho_p$ if $\epsilon < (3 - \sqrt{3})/6$ ($\approx 21\%$), (b) $\rho_1 = \dots = \rho_{p-1} > \rho_p$ if $\epsilon > (3 - \sqrt{3})/6$, (c) $\rho_1 = \rho_2 = \dots = \rho_p$ if $\epsilon = (3 - \sqrt{3})/6$.

Moreover, if (a) (resp. (b)) holds then the eigenvector associated with ρ_1 (resp. ρ_p) is proportional to $\Sigma_1^{-1} \mu$.

Symmetric contamination of a Gaussian distribution Proposition

$$\mathbf{X} \sim (1 - \epsilon) \, \mathcal{N}(\mathbf{0}_{p}, \mathbf{\Sigma}_{21}) + rac{\epsilon}{2} \, \mathcal{N}(\delta \mathbf{e}_{1}, \mathbf{\Sigma}_{22}) + rac{\epsilon}{2} \, \mathcal{N}(-\delta \mathbf{e}_{1}, \mathbf{\Sigma}_{22})$$

with $\boldsymbol{\Sigma}_{21} = \operatorname{diag}(\sigma_{11}^2, \sigma_{12}^2, \dots, \sigma_{12}^2)$, $\boldsymbol{\Sigma}_{22} = \operatorname{diag}(\sigma_{21}^2, \sigma_{22}^2, \dots, \sigma_{22}^2)$ and $\delta \neq 0$.

The eigenvalues of $COV^{-1}(\mathbf{X})COV_4(\mathbf{X})$ are such that either:

(a)
$$\rho_1 > \rho_2 = \dots = \rho_p$$
,
(b) $\rho_1 = \dots = \rho_{p-1} > \rho_p$,
(c) $\rho_1 = \rho_2 = \dots = \rho_p$.
with $\rho_1 = \frac{1}{p+2} \left(\frac{3(1-\epsilon)\sigma_{11}^4 + \epsilon(3\sigma_{21}^4 + 6\sigma_{21}^2\delta^2 + \delta^4)}{((1-\epsilon)\sigma_{11}^2 + \epsilon(\sigma_{21}^2 + \delta^2))^2} + p - 1 \right)$
and $\rho_2 = \frac{1}{p+2} \left(\frac{3((1-\epsilon)\sigma_{12}^4 + \epsilon\sigma_{22}^4)}{((1-\epsilon)\sigma_{12}^2 + \epsilon\sigma_{22}^2)^2} + p - 1 \right)$.

Moreover, if (a) (resp. (b)) holds then the eigenvector associated with ρ_1 (resp. ρ_p) is proportional to **e**₁.

Corollary: with $\Sigma_{21} = \Sigma_{22} = I_p$, (a) holds if $\epsilon < 1/3$.

Scale-shift outlier model ($q \le p$)

Proposition

$$\mathbf{X} \sim (1-\epsilon) \mathcal{N}(\mathbf{0}_{m{
ho}}, \mathbf{I}_{m{
ho}}) + \epsilon \mathcal{N}(\mathbf{0}_{m{
ho}}, \mathbf{\Sigma}_5)$$

with $\epsilon < 0.5$, $\Sigma_5 = \text{diag}(\alpha \mathbf{I}_q, \mathbf{I}_{p-q})$, q < p and $\alpha > 1$.

The eigenvalues of $\text{COV}^{-1}(\mathbf{X})\text{COV}_4(\mathbf{X})$ are such that:

$$\rho_1(\mathbf{F}_{\mathbf{X}}) = \cdots = \rho_q(\mathbf{F}_{\mathbf{X}}) > \rho_{q+1}(\mathbf{F}_{\mathbf{X}}) = \cdots = \rho_p(\mathbf{F}_{\mathbf{X}})$$

Moreover, the eigenvectors associated with the *q* largest eigenvalues span the subspace spanned by $\{\mathbf{e}_1, \ldots, \mathbf{e}_q\}$.

Remark: if q = p then all the eigenvalues are equal.

ICS (sample version)

Simultaneous diagonalization of two scatter matrices V_{1,n} and V_{2,n}:

 $\mathbf{V}_{1,n}^{-1}\mathbf{V}_{2,n}\mathbf{B}_n'=\mathbf{B}_n'\mathbf{D}_n$

where the diagonal matrix \mathbf{D}_n contains the eigenvalues ρ_1, \ldots, ρ_p of $\mathbf{V}_{1,n}^{-1}\mathbf{V}_{2,n}$ in decreasing order and $\mathbf{B}_n = (\mathbf{b}_1, \ldots, \mathbf{b}_p)'$ contains the corresponding eigenvectors as its rows such that: $\mathbf{B}_n \mathbf{V}_{1,n} \mathbf{B}'_n = \mathbf{I}_p$.

► The (affine) invariant coordinates are:

 $\mathbf{z}_i = \mathbf{B}_n(\mathbf{x}_i - \mathbf{m}_{1,n})$

with $\mathbf{m}_{1,n}$ being the location estimator associated with $\mathbf{V}_{1,n}$.

► For *k* selected ICS components, we define an ICS distance as:

$$\mathsf{ICSD}^2_{\mathbf{V}_{1,n}^{-1}\mathbf{V}_{2,n}}(\mathbf{x}_i,k) = \mathbf{z}_{i,k}'\mathbf{z}_{i,k}$$

with $\mathbf{z}_{i,k} = \mathbf{B}_{n,k}(\mathbf{x}_i - \mathbf{m}_{1,n})$ and $\mathbf{B}_{n,k}$ contains the first k rows of \mathbf{B}_n .

Relationship with the MD²

For k selected ICS components, we define an ICS distance as:

$$\mathsf{ICSD}^2_{\mathbf{V}_{1,n}^{-1}\mathbf{V}_{2,n}}(\mathbf{x}_i,k) = \mathbf{z}_{i,k}'\mathbf{z}_{i,k}$$

with $\mathbf{z}_{i,k} = \mathbf{B}_{n,k}(\mathbf{x}_i - \mathbf{m}_{1,n})$ and $\mathbf{B}_{n,k}$ contains the first k rows of \mathbf{B}_n .

Property

$$\mathsf{ICSD}^2_{\mathrm{COV}(\mathbf{X}_n)^{-1}\mathrm{COV}_4(\mathbf{X}_n)}(\mathbf{x}_i, \boldsymbol{p}) = \mathsf{MD}^2(\mathbf{x}_i)$$

If the structure of outlyingness is contained on a subspace of dimension q less than p, then ICS has an advantage over MD if we select k = q components.

20 obs $\sim \mathcal{N}_{\rho}(\mu_1, \mathbf{W})$ & 980 obs $\sim \mathcal{N}_{\rho}(\mathbf{0}_{\rho}, \mathbf{W})$

with $\mu_1 = (6, 0, \dots, 0)'$, $\mathbf{W} = \text{diag}(1, 4, \dots, 4)$, n = 1000, 2% of outliers and p = 6, 25, 50.



Selection of the Invariant Coordinates

As we look only for a small proportion of outliers, the outliers should be found in the first components.

Approaches:

- Based on the analysis of the eigenvalues:
 - Visually, using a scree plot.
 - Using asymptotic distribution of the eigenvalues.
 - Using quasi inferential procedures (parallel analysis).
- Based on the analysis of the Invariant Components:
 - Using marginal normality tests.

In this context of particular sequential multiple testing, we apply the Bonferroni correction on the significance level: $\alpha_i = \alpha/i$ for i = 1, ..., p with $\alpha = 5\%$.

The ICSOutlier and ICSShiny R packages

Detection of a small proportion of outliers via ICS can be easily done using our package ICSOutlier which is available on CRAN or with the ICSShiny application.

There the user can:

- Choose the scatter matrices $V_{1,n}$ and $V_{2,n}$.
- Choose the ICS components visually, using parallel analysis or marginal normality testing.
- Explore the invariant components.
- Identify outliers based on a cut-off obtained from simulations.

Simulations & Real Examples

We conducted an extensive simulation study comparing

- MD and robust MD, and PCA based outlier detection methods with ICS
- Concerning ICS, we evaluated:
 - different scatter combinations.
 - different ways to select the ICS components.

Conclusion: ICS and especially the scatter combination COV-COV₄ works well and has interesting theoretical properties.

High Tech Parts Example I

- 902 high-tech parts characterized by 88 numerical tests (available in ICSOutlier).
- All parts have been sold (considered flawless) but afterwards two parts have been returned due to malfunctions ⇒ two quality defects.



High Tech Parts Example II



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Conclusion

- Exhibit a limitation of the Mahalanobis distance when p is large and when outliers lie on a subspace.
- Propose a methodology for outlier detection with ICS.
- Generalize ICS to semi-definite positive scatter matrices for data not in general position.
- Perpectives: extend the theory and package to be able to handle also large fractions of outliers (e.g. deriving results for mixtures with three or more components), propose a sparse ICS.